

Some observations on high-dimensional partial differential equations with Barron data

Weinan E, Stephan Wojtowytsch

Princeton University

July 28, 2021

MSML 2021





There are many methods to solve 'low-dimensional' PDEs, but few for very high-dimensional problems (many body quantum systems in physics or computational chemistry, applications in finance, ...)



- There are many methods to solve 'low-dimensional' PDEs, but few for very high-dimensional problems (many body quantum systems in physics or computational chemistry, applications in finance, ...)
- Neural networks have been very successful in beating the 'curse of dimensionality' in other fields and are quickly becoming more popular in solving high-dimensional PDEs as well
 - ▶ E-Han-Jentzen: Deep learning-based numerical methods for high-dimensional parabolic partial differential equations and backward stochastic differential equations, 2017
 - E-Yu: The Deep Ritz method: A deep learning-based numerical algorithm for solving variational problems, 2017
 - ▶ Han-Jentzen-E: Solving high-dimensional partial differential equations using deep learning, 2017
 - ► ...



- There are many methods to solve 'low-dimensional' PDEs, but few for very high-dimensional problems (many body quantum systems in physics or computational chemistry, applications in finance, ...)
- Neural networks have been very successful in beating the 'curse of dimensionality' in other fields and are quickly becoming more popular in solving high-dimensional PDEs as well
 - ▶ E-Han-Jentzen: Deep learning-based numerical methods for high-dimensional parabolic partial differential equations and backward stochastic differential equations, 2017
 - E-Yu: The Deep Ritz method: A deep learning-based numerical algorithm for solving variational problems, 2017
 - ▶ Han-Jentzen-E: Solving high-dimensional partial differential equations using deep learning, 2017
 - ▶ ...
- It can be proved rigorously in some cases that certain classes of neural networks can approximate the solution of a PDE without the CoD.



- There are many methods to solve 'low-dimensional' PDEs, but few for very high-dimensional problems (many body quantum systems in physics or computational chemistry, applications in finance, ...)
- Neural networks have been very successful in beating the 'curse of dimensionality' in other fields and are quickly becoming more popular in solving high-dimensional PDEs as well
 - ▶ E-Han-Jentzen: Deep learning-based numerical methods for high-dimensional parabolic partial differential equations and backward stochastic differential equations, 2017
 - E-Yu: The Deep Ritz method: A deep learning-based numerical algorithm for solving variational problems, 2017
 - ▶ Han-Jentzen-E: Solving high-dimensional partial differential equations using deep learning, 2017
 - ► ...
- It can be proved rigorously in some cases that certain classes of neural networks can approximate the solution of a PDE without the CoD.
- Can we show that solutions to PDEs lie in certain 'simple' function spaces, in which elements can be approximated by neural network models without the CoD?
 - 1. Regularity of solutions
 - 2. Approximation of elements in function space
 - 3. Numerical method



- There are many methods to solve 'low-dimensional' PDEs, but few for very high-dimensional problems (many body quantum systems in physics or computational chemistry, applications in finance, ...)
- Neural networks have been very successful in beating the 'curse of dimensionality' in other fields and are quickly becoming more popular in solving high-dimensional PDEs as well
 - ▶ E-Han-Jentzen: Deep learning-based numerical methods for high-dimensional parabolic partial differential equations and backward stochastic differential equations, 2017
 - E-Yu: The Deep Ritz method: A deep learning-based numerical algorithm for solving variational problems, 2017
 - ▶ Han-Jentzen-E: Solving high-dimensional partial differential equations using deep learning, 2017

► ...

- It can be proved rigorously in some cases that certain classes of neural networks can approximate the solution of a PDE without the CoD.
- Can we show that solutions to PDEs lie in certain 'simple' function spaces, in which elements can be approximated by neural network models without the CoD?

1. Regularity of solutions

- 2. Approximation of elements in function space
- 3. Numerical method

Barron spaces



Definition

A function is called a Barron function if there exists a probability distribution π such that

$$f(x) = \mathbb{E}_{(a,w,b)\sim\pi} \left[a\sigma(w^T x + b) \right], \qquad \mathbb{E}_{(a,w,b)\sim\pi} \left[|a|(|w| + |b|) \right] < \infty.$$

Theorem (E-Ma-Wu '17)

If \mathbb{P} is a probability distribution on \mathbb{R}^d and $f : \mathbb{R}^d \to \mathbb{R}$ is a Barron function, then for every $m \in \mathbb{N}$ there exist weights $(a_i, w_i, b_i)_{i=1}^m$ such that

$$\left\|f-\sum_{i=1}^m a_i\sigma(w_i^Tx+b_i)\right\|_{L^2(\mathbb{P})} \leq \frac{\|f\|_{\mathcal{B}}}{\sqrt{m}} \sqrt{\int_{\mathbb{R}^d} 1+|x|^2\,\mathrm{d}\mathbb{P}}$$

Proof. Monte-Carlo integration.



Theorem

Assume that $f \in \mathcal{B}$ and

$$(-\Delta + \lambda^2)u = f$$

for $\lambda > 0$. Then $\|u\|_{\mathcal{B}} \le \lambda^{-2} \|f\|_{\mathcal{B}}$ if σ has finite limits at $\pm \infty$ and

$$\|u\|_{\mathcal{B}} \leq \left[\lambda^{-2} + 2\,\lambda^{-3}\right] \|f\|_{\mathcal{B}}.$$

if $\sigma = \text{ReLU}$.

Proof.

Convolution with the 3d Green's function $G(x) = \frac{e^{-\lambda|x|}}{4\pi |x|}$. Use that Barron functions are superpositions of 1d profiles.

Heat equation



Consider

$$u_t - \Delta u = 0 \quad t > 0 \\ u = u_0 \quad t > 0$$

With $u_0(x) = \mathbb{E}_{(a,w,b)} [a\sigma(w^T x + b)]$. Then

$$u(t,x) = \frac{1}{(4\pi)^{d/2}} \mathbb{E}_{(a,w,b)} \left[\int_{\mathbb{R}^d} \exp\left(-y^2\right) a\sigma\left(w^T \left(x - \sqrt{t} y\right) + b\right) dy \right]$$

is a Barron function

- 1. in x and \sqrt{t} with norm $||u||_{\mathcal{B}} \leq 2 ||f||_{\mathcal{B}}$.
- 2. in x with Barron norm $\|u(t,\cdot)\|_{\mathcal{B}} \leq 2(1+\sqrt{t}) \|u\|_{\mathcal{B}}$ for fixed t > 0.

Remark

Only the second estimate carries over to the inhomogeneous heat equation as

$$\|u_{inhom}(t,\cdot)\|_{\mathcal{B}} \leq C \left[1+t^{3/2}\right] \sup_{0 < s < t} \|f(s,\cdot)\|_{\mathcal{B}}.$$



Consider

$$\left\{ \begin{array}{rrr} u_t-\Delta u &= |\nabla u|^2 \quad t>0 \\ u &= u_0 \quad t=0 \end{array} \right., \qquad \left\{ \begin{array}{rrr} v_t-\Delta v &= 0 \quad t>0 \\ v &= \exp(u_0) \quad t=0. \end{array} \right.$$

Then $u(t,x) = \log (v(t,x))$.

1. On bounded intervals, we can represent exp : $(-\infty, R] \to \mathbb{R}$ and log : $[\varepsilon, 1/\varepsilon] \to \mathbb{R}$ as Barron functions.



Consider

$$\left\{\begin{array}{rrr} u_t-\Delta u&=|\nabla u|^2 \quad t>0\\ u&=u_0 \quad t=0\end{array}, \quad \left\{\begin{array}{rrr} v_t-\Delta v&=0 \quad t>0\\ v&=\exp(u_0) \quad t=0.\end{array}\right.\right.$$

Then $u(t,x) = \log (v(t,x))$.

- 1. On bounded intervals, we can represent exp : $(-\infty, R] \to \mathbb{R}$ and log : $[\varepsilon, 1/\varepsilon] \to \mathbb{R}$ as Barron functions.
- 2. If $f = A \circ \sigma \circ W$ and $g = \tilde{A} \circ \sigma \circ \tilde{W}$ are finite two-layer networks, their composition

$$f \circ g = A \circ \sigma \circ (W \circ \tilde{A}) \circ \sigma \circ \tilde{W}$$

is a three-layer network, since the composition of linear maps is linear.



Consider

$$\left\{\begin{array}{rrr} u_t-\Delta u&=|\nabla u|^2 \quad t>0\\ u&=u_0 \quad t=0\end{array}, \quad \left\{\begin{array}{rrr} v_t-\Delta v&=0 \quad t>0\\ v&=\exp(u_0) \quad t=0.\end{array}\right.\right.$$

Then $u(t,x) = \log (v(t,x))$.

- 1. On bounded intervals, we can represent exp : $(-\infty, R] \to \mathbb{R}$ and log : $[\varepsilon, 1/\varepsilon] \to \mathbb{R}$ as Barron functions.
- 2. If $f = A \circ \sigma \circ W$ and $g = \tilde{A} \circ \sigma \circ \tilde{W}$ are finite two-layer networks, their composition

$$f \circ g = A \circ \sigma \circ (W \circ \tilde{A}) \circ \sigma \circ \tilde{W}$$

is a three-layer network, since the composition of linear maps is linear.

3. Similarly, we can write $u = \phi \circ \exp \circ u_0$ where ϕ is a Barron function which includes the logarithm and the convolution with the heat kernel.



Consider

$$\left\{\begin{array}{rrr} u_t-\Delta u&=|\nabla u|^2 \quad t>0\\ u&=u_0 \quad t=0\end{array}, \quad \left\{\begin{array}{rrr} v_t-\Delta v&=0 \quad t>0\\ v&=\exp(u_0) \quad t=0.\end{array}\right.\right.$$

Then $u(t,x) = \log (v(t,x))$.

- 1. On bounded intervals, we can represent exp : $(-\infty, R] \to \mathbb{R}$ and log : $[\varepsilon, 1/\varepsilon] \to \mathbb{R}$ as Barron functions.
- 2. If $f = A \circ \sigma \circ W$ and $g = \tilde{A} \circ \sigma \circ \tilde{W}$ are finite two-layer networks, their composition

$$f \circ g = A \circ \sigma \circ (W \circ \tilde{A}) \circ \sigma \circ \tilde{W}$$

is a three-layer network, since the composition of linear maps is linear.

- 3. Similarly, we can write $u = \phi \circ \exp \circ u_0$ where ϕ is a Barron function which includes the logarithm and the convolution with the heat kernel.
- 4. In a function space \mathcal{W}^3 for three-layer neural networks (the space of 'tree-like' functions), the estimate

$$\|u\|_{\mathcal{W}^3} \leq \exp\left(\sup_{x\in\mathbb{R}^d} u_0(x) - \inf_{x\in\mathbb{R}^d} u_0(x)\right) \|u_0\|_{\mathcal{B}}$$

holds for bounded Barron initial data as a Barron function in \sqrt{t} , x.



Assume that u solves

$$\begin{cases} -\Delta u &= 0 & x \in B_1(0) \\ u &= \operatorname{ReLU}(x_1) & x \in \partial B_1(0). \end{cases}$$

Then

1. If $u \in \mathcal{B}$, it can be defined (non-uniquely) on the whole space by a representation formula $u(x) = \mathbb{E}_{(w,b)\sim\pi}\sigma(w^T x + b).$



Assume that u solves

$$\begin{cases} -\Delta u &= 0 \qquad x \in B_1(0) \\ u &= \operatorname{ReLU}(x_1) \quad x \in \partial B_1(0). \end{cases}$$

Then

- 1. If $u \in \mathcal{B}$, it can be defined (non-uniquely) on the whole space by a representation formula $u(x) = \mathbb{E}_{(w,b)\sim\pi}\sigma(w^T x + b).$
- 2. The equator $\{x \in \partial B_1(0) : x_1 = 0\}$ is part of the set where *u* is not differentiable, but the central plane $\{x \in B_1(0) : x_1 = 0\}$ is not.



Assume that u solves

$$\begin{cases} -\Delta u &= 0 \qquad x \in B_1(0) \\ u &= \operatorname{ReLU}(x_1) \quad x \in \partial B_1(0). \end{cases}$$

Then

- 1. If $u \in \mathcal{B}$, it can be defined (non-uniquely) on the whole space by a representation formula $u(x) = \mathbb{E}_{(w,b)\sim\pi}\sigma(w^T x + b).$
- 2. The equator $\{x \in \partial B_1(0) : x_1 = 0\}$ is part of the set where u is not differentiable, but the central plane $\{x \in B_1(0) : x_1 = 0\}$ is not.
- 3. The singular set of a Barron function is a countable union of affine subspaces of dimension $0 \le k \le d-1$ (structure theorem for Barron functions, E-W '20).

So, if d > 2, u is not a Barron function.



- 1. For translation-invariant linear PDEs, solutions often (but not always) lie in Barron space.
 - Examples: Heat equation, screened Poisson equation $-\Delta u + \lambda u = f$ for $\lambda > 0$.
 - Counterexample: Poisson equation, since the solution $u(x) = \frac{1}{6} \sigma(x_1)^3$ of $-\Delta u = \sigma(x_1)$ grows too fast at infinity.



- 1. For translation-invariant linear PDEs, solutions often (but not always) lie in Barron space.
 - Examples: Heat equation, screened Poisson equation $-\Delta u + \lambda u = f$ for $\lambda > 0$.
 - Counterexample: Poisson equation, since the solution $u(x) = \frac{1}{6} \sigma(x_1)^3$ of $-\Delta u = \sigma(x_1)$ grows too fast at infinity.
- 2. Boundary conditions break translation invariance. Even harmonic functions with ReLU boundary values are not in Barron space.
 - ► It is unknown whether the solution can be represented by e.g. the composition of Barron functions.
 - ► There are further positive results in this direction by Lu and Lu ('20, '21) for elliptic equations and Schrödinger eigenvalue problems with Neumann boundary condition and *spectral* Barron spaces on the unit hypercube.



- 1. For translation-invariant linear PDEs, solutions often (but not always) lie in Barron space.
 - Examples: Heat equation, screened Poisson equation $-\Delta u + \lambda u = f$ for $\lambda > 0$.
 - Counterexample: Poisson equation, since the solution $u(x) = \frac{1}{6} \sigma(x_1)^3$ of $-\Delta u = \sigma(x_1)$ grows too fast at infinity.
- 2. Boundary conditions break translation invariance. Even harmonic functions with ReLU boundary values are not in Barron space.
 - ► It is unknown whether the solution can be represented by e.g. the composition of Barron functions.
 - ► There are further positive results in this direction by Lu and Lu ('20, '21) for elliptic equations and Schrödinger eigenvalue problems with Neumann boundary condition and *spectral* Barron spaces on the unit hypercube.
- 3. Nonlinear PDEs may need deeper networks.