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CONSTRUCTION OF OPTIMAL SPECTRAL METHODS IN PHASE RETRIEVAL

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Antoine Maillard

Joint work with Florent Krzakala, Yue M. Lu & Lenka Zdeborová

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PHASE RETRIEVAL

Goal: Recover a d -dimensional signal X^* from n data points $\{\Phi_\mu, Y_\mu\}_{\mu=1}^n$ generated as:

Generalized Linear Model (GLM)

Observations $Y_\mu \in \mathbb{R}$

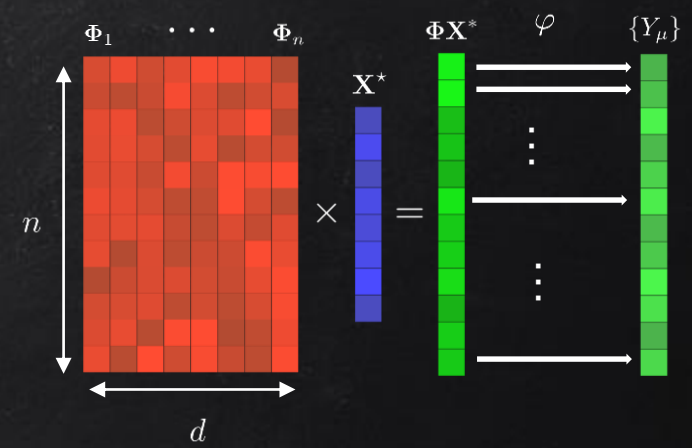
Real / Complex
 $\beta = 1$ $\beta = 2$

$$Y_\mu \sim P_{\text{out}} \left(\cdot \left| \frac{1}{\sqrt{d}} \sum_{i=1}^d \Phi_{\mu i} X_i^* \right|^2 \right) \quad \mu \in \{1, \dots, n\}$$

(Probabilistic) channel with possible noise.

Sensing matrix (real/complex)

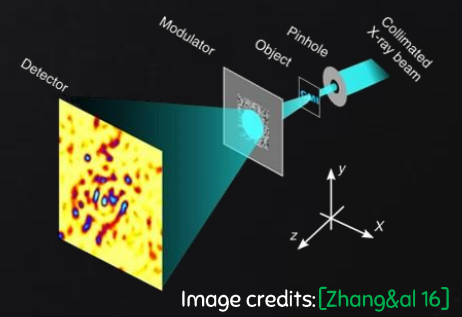
Signal (real/complex), d -dimensional



In **phase retrieval**, one measures the modulus $P_{\text{out}}(y|z) = P_{\text{out}}(y||z|)$, e.g. **noiseless** $Y_\mu = \frac{1}{d} |(\Phi X^*)_\mu|^2$; **Poisson-noise** $Y_\mu \sim \text{Pois}(\Lambda |(\Phi X^*)_\mu|^2 / d)$.

Arises in **signal processing, statistical estimation, optics, X-ray crystallography, astronomy, microscopy...**

How to solve this problem efficiently in high dimensions? $n, d \rightarrow \infty$



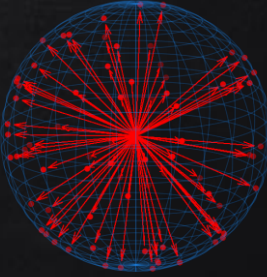
- SDP relaxations [Candès&al '15a&b, Waldspurger&al '15, Goldstein&al '18, ...]
- Non-convex optimization procedures [Netrapalli&al '15, Candès&al '15c, ...]
- Approximate Message-Passing [Barbier&al '19, A.M.&al '20]

Computationally heavy / Need informed initialization

Spectral methods

[Mondelli&al '18, Luo&al '18, Dudeja&al '19, ...]

CONSTRUCTION OF SPECTRAL METHODS



Our model: The matrix Φ is **right-orthogonally (unitarily) invariant**, i.e. delocalized right-eigenvectors: $\forall \mathbf{U}, \Phi \stackrel{d}{=} \Phi \mathbf{U}$

The bulk of eigenvalues of $\Phi^\dagger \Phi / d$ converges to a distribution $\nu(x)$, as $n, d \rightarrow \infty$ with $n/d \rightarrow \alpha > 0$.

Examples: Gaussian matrices, product of Gaussians, random column-orthogonal/unitary, any $\Phi \equiv \mathbf{U} \mathbf{S} \mathbf{V}^\dagger$ with $S_i^2 \stackrel{\text{i.i.d.}}{\sim} \nu$.

Given a phase retrieval problem, we want an **optimal spectral method (among all possible ones)** in terms of estimation error:

$$\text{MSE} \equiv \frac{1}{d\rho} \|\mathbf{X}^* - \hat{\mathbf{X}}_{\text{spectral}}\|^2$$

This talk: Three different strategies, related to the **statistical physics** approach to high-dimensional inference.

- Method I: “Naïve” generalization of what is known for Gaussian matrices.
- Method II: Linearization of **message-passing** algorithms.
- Method III: **Bethe Hessian** analysis from the Thouless–Anderson–Palmer [TAP77] free energy.

METHOD I

[Chen&al '15, Wang&al '16, Zhang&al '17, Mondelli&al '19, Luo&al '19, Dudeja&al '19]

$$y_\mu \sim P_{\text{out}}\left(\cdot \mid \frac{1}{\sqrt{d}} \sum_{i=1}^d \Phi_{\mu i} X_i^*\right)$$

Most previous works reduced to methods of the type

$$\mathbf{M}(\mathcal{T}) \equiv \frac{1}{d} \sum_{\mu=1}^n \mathcal{T}(y_\mu) \Phi_\mu \Phi_\mu^\dagger$$

For Gaussian matrices Φ the optimal method in this class is given by

$$\mathcal{T}_{\text{Gaussian}}^*(y) \equiv \frac{\partial_\omega g_{\text{out}}(y_\mu, 0, \rho)}{1 + \rho \partial_\omega g_{\text{out}}(y_\mu, 0, \rho)}$$

- In **noiseless phase retrieval** one has $\mathcal{T}_{\text{Gaussian}}^*(y) = 1 - 1/y$.

$$\partial_\omega g_{\text{out}}(y_\mu, 0, \sigma^2) = -\frac{1}{\sigma^2} + \frac{1}{\sigma^4} \frac{\int_{\mathbb{K}} dx e^{-\frac{\beta}{2\sigma^2}|x|^2} |x|^2 P_{\text{out}}(y_\mu|x)}{\int_{\mathbb{K}} dx e^{-\frac{\beta}{2\sigma^2}|x|^2} P_{\text{out}}(y_\mu|x)}$$

- We can naively use it for all matrices: $\mathbf{M}_{\text{naive}} \equiv \mathbf{M}(\mathcal{T}_{\text{Gaussian}}^*)$

($\mathbb{K} = \mathbb{R}, \mathbb{C}$)

METHOD II

[Schniter&al '16, A.M.&al '20]: For GLMs with rotationally-invariant matrices, the best-known polynomial-time algorithm is **Generalized Vector Approximate Message-Passing** (G-VAMP).

↓ Linearization procedure

Linearized Approximate Message-Passing (LAMP) spectral method.

$$\mathbf{M}_{\text{LAMP}} \equiv \frac{\rho \langle \lambda \rangle_\nu}{\alpha} \left(\frac{\alpha}{\langle \lambda \rangle_\nu} \frac{\Phi \Phi^\dagger}{d} - \mathbf{I}_n \right) \text{Diag}(\{\partial_\omega g_{\text{out}}(y_\mu, 0, \rho \langle \lambda \rangle_\nu / \alpha)\}) \longrightarrow \hat{\mathbf{x}} \equiv \frac{\Phi^\dagger \text{Diag}(\{\partial_\omega g_{\text{out}}(y_\mu, 0, \rho \langle \lambda \rangle_\nu / \alpha)\}) \hat{\mathbf{u}}}{\|\Phi^\dagger \text{Diag}(\{\partial_\omega g_{\text{out}}(y_\mu, 0, \rho \langle \lambda \rangle_\nu / \alpha)\}) \hat{\mathbf{u}}\|} \sqrt{d\rho}.$$

\mathbf{M}_{LAMP} is a $n \times n$ non-Hermitian matrix (complex spectrum).

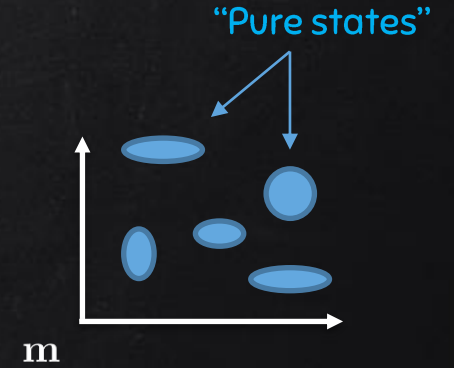
$\hat{\mathbf{u}}$: top eigenvector of \mathbf{M}_{LAMP} .

Similar approaches in **community detection** [Krzakala&al '13], **phase retrieval with unitary matrices** [Ma&al '21] or **spiked matrix estimation** [Aubin&al '20].

METHOD III: TAP LANDSCAPE AND BETHE HESSIAN

Thouless-Anderson-Palmer approach [TAP77]

- The posterior measure of $\mathbf{x}|Y$ (the *Gibbs measure*) decomposes along **pure states**.
- These pure states can be found by “tilting” the measure, imposing $m_i = \langle x_i \rangle$ and $\sigma_i^2 = \text{Var}(x_i)$:
They are the **maxima of the free entropy** of this constrained measure, as a function of (\mathbf{m}, σ) .



- TAP free entropy for **rotationally-invariant generalized linear models** derived in [A.M.&al '19], generalizing [Parisi&Potters '95]:

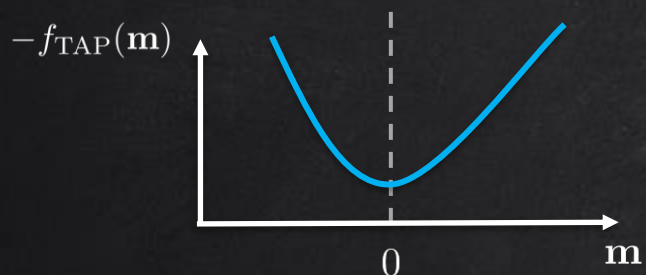
Involved but explicit!

$$f_{\text{TAP}}(\mathbf{m}) = \sup_{\sigma \geq 0} \sup_{\substack{\mathbf{g} \in \mathbb{K}^n \\ r \geq 0}} \text{extr}_{\substack{\omega \in \mathbb{K}^n \\ b \geq 0}} \text{extr}_{\substack{\lambda \in \mathbb{K}^d \\ \gamma \geq 0}} \left[\frac{\beta}{d} \sum_{i=1}^d \lambda_i \cdot m_i + \frac{\beta\gamma}{2d} (d\sigma^2 + \sum_{i=1}^d |m_i|^2) - \frac{\beta}{d} \sum_{\mu=1}^n \omega_\mu \cdot g_\mu - \frac{\beta b}{2d} \left(\sum_{\mu=1}^n |g_\mu|^2 - \alpha dr \right) + \frac{1}{d} \sum_{i=1}^d \ln \int_{\mathbb{K}} P_0(dx) e^{-\frac{\beta\gamma}{2}|x|^2 - \beta\lambda_i \cdot x} \right. \\ \left. + \frac{\alpha}{n} \sum_{\mu=1}^n \ln \int_{\mathbb{K}} \frac{dh}{\left(\frac{2\pi b}{\beta}\right)^{\beta/2}} P_{\text{out}}(y_\mu|h) e^{-\frac{\beta|h-\omega_\mu|^2}{2b}} + \frac{\beta}{d} \sum_{i=1}^d \sum_{\mu=1}^n g_\mu \cdot \left(\frac{\Phi_{\mu i}}{\sqrt{d}} m_i \right) + \beta F(\sigma^2, r) \right].$$

$$F(x, y) \equiv \inf_{\zeta_x, \zeta_y > 0} \left[\frac{\zeta_x x}{2} + \frac{\alpha \zeta_y y}{2} - \frac{\alpha - 1}{2} \ln \zeta_y - \frac{1}{2} \langle \ln(\zeta_x \zeta_y + \lambda) \rangle_\nu \right] - \frac{1}{2} \ln x - \frac{\alpha}{2} \ln y - \frac{1 + \alpha}{2}.$$

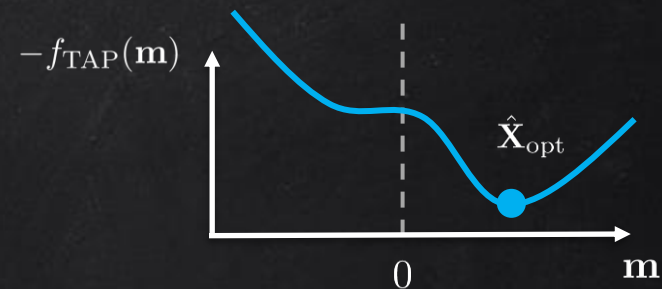
Weak-recovery impossible

Global maximum of f_{TAP} in $\mathbf{m} = 0$: the uninformative “paramagnetic” point.



Weak-recovery possible

$\mathbf{m} = 0$ is an unstable stationary point of f_{TAP} , which has a global maximum in $\mathbf{m} \neq 0$ (optimal estimator).



A spectral method can only use the physical information available in the uninformative point $\mathbf{m} = 0$.

Compute the Hessian of f_{TAP} at the paramagnetic point.

Constructive derivation of a spectral method that is conjectured to be optimal.

TAP - Bethe Hessian spectral method.

$$\mathbf{M}_{\text{TAP}} \equiv -d\nabla^2 f_{\text{TAP}}(\mathbf{m} = 0) = -\frac{1}{\rho} \mathbf{I}_d + \frac{1}{d} \sum_{\mu=1}^n \frac{\partial_{\omega} g_{\text{out}}(y_{\mu}, 0, \rho \langle \lambda \rangle_{\nu} / \alpha)}{1 + \frac{\rho \langle \lambda \rangle_{\nu}}{\alpha} \partial_{\omega} g_{\text{out}}(y_{\mu}, 0, \rho \langle \lambda \rangle_{\nu} / \alpha)} \Phi_{\mu} \Phi_{\mu}^{\dagger}$$

Similar to previous strategies in community detection. [Saade&al'14]

OPTIMAL SPECTRAL METHOD

From the Bethe Hessian analysis

$$\mathbf{M}(\mathcal{T}) \equiv \frac{1}{d} \sum_{\mu=1}^n \mathcal{T}(y_{\mu}) \Phi_{\mu} \Phi_{\mu}^{\dagger}$$

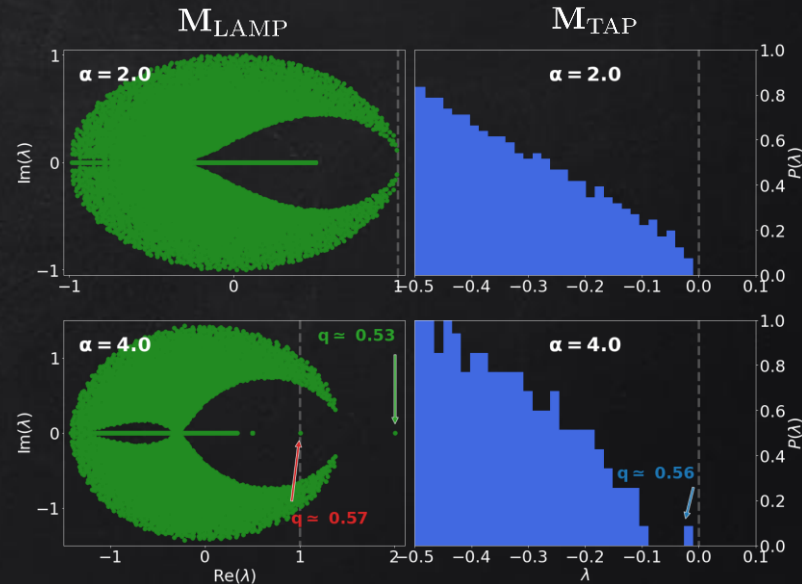
Main conjecture: For any right-orthogonally invariant sensing matrix, the optimal spectral method (in terms of weak-recovery threshold and achieved error) belongs to the class of matrices $\mathbf{M}(\mathcal{T})$ and is attained in:

$$\mathcal{T}^*(y) = \frac{\partial_{\omega} g_{\text{out}}(y_{\mu}, 0, \rho\langle\lambda\rangle_{\nu}/\alpha)}{1 + \frac{\rho\langle\lambda\rangle_{\nu}}{\alpha} \partial_{\omega} g_{\text{out}}(y_{\mu}, 0, \rho\langle\lambda\rangle_{\nu}/\alpha)}$$

- The optimal method is the “naïve” generalization of Method I.
- We did not assume anything on the form of the method: **we confirm the validity of the restriction of previous works on spectral methods to the class of matrices $\mathbf{M}(\mathcal{T})$!**
- The optimal spectral method does not depend on the **spectrum of the sensing matrix (apart from a global scaling)**, nor on the **sampling ratio α !**

➔ **Consequences for practitioners: one only needs to know the observation channel to construct the method!**

Complex Gaussian Φ and Poisson noise $P_{\text{out}}(y|z) = e^{-\Lambda|z|^2} \sum_{k=0}^{\infty} \delta(y-k) \frac{\Lambda^k |z|^{2k}}{k!}$



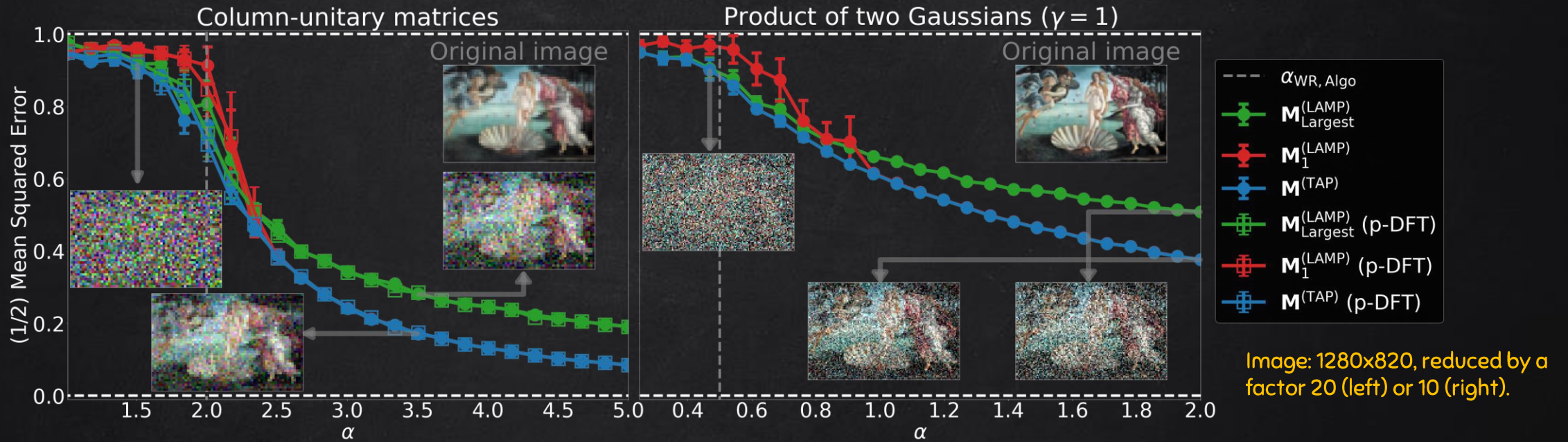
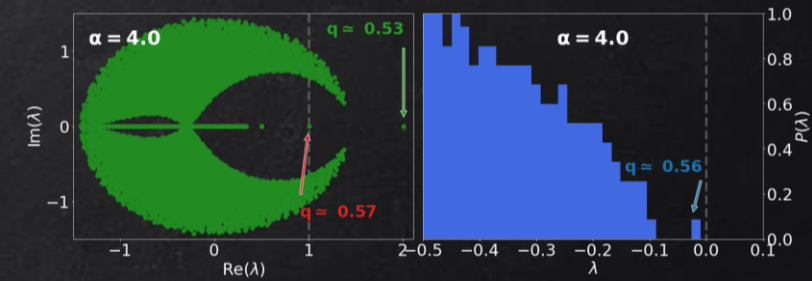
$$\Lambda = 1$$

$$q = \frac{1}{d} \sum_{i=1}^d X_i^* \hat{x}_i$$

- The optimal method corresponds to **marginal stability** in both \mathbf{M}_{TAP} and \mathbf{M}_{LAMP} .
- **Puzzle:** the dominant eigenvector of \mathbf{M}_{LAMP} is a **suboptimal estimator!**

SPECTRAL METHODS PERFORMANCE

Noiseless complex phase retrieval $Y_\mu = \frac{1}{d} |\Phi X^*|^2$



- $\hat{x}_{\text{LAMP}}(\lambda = 1) \iff \hat{x}_{\text{TAP}}$, achieving the best overlap. Otherwise $\hat{x}_{\text{LAMP}}(\lambda_{\text{max}})$ is suboptimal in terms of MSE.
- Our theory stays valid for **matrices with controlled structure** (partial DFT \equiv randomly subsampled DFT).
- For partial DFT matrices, we use the method as initialization of a gradient-descent procedure: **perfect recovery** at $\alpha \in (3, 4)$, while the best polynomial-time algorithm achieves $\alpha_{\text{PR}} \simeq 2, 3$ [A.M&a'20]. **Very competitive while computationally cheap!**

CONCLUSION AND PERSPECTIVES

Main contributions

- Constructive derivation of a **conjecturally optimal spectral method** in generic phase retrieval problems, in a framework that encompasses real/complex variables and a wide variety of sensing matrices.
- Our results apply to **randomly subsampled DFT** matrices and to **real image** (i.e. structured signal) recovery.
- We use two fundamentally equivalent approaches – **message-passing linearization** and **Bethe Hessian analysis** – that yield the same optimal performance, associated with a **marginal stability of the linear dynamics**.

Open questions remain, e.g. the “marginality vs instability” puzzle: In M_{LAMP} the optimal method is “hidden” inside the bulk and marginally stable, while the dominant eigenvalue is unstable and suboptimal.

THANK YOU !